

PLANE RECTIFIABLE CURVES: OLD AND NEW

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ABSTRACT. In this note we recall the classical notion of an algebraically rectifiable plane curve going back to J. A. Serret, E. Laguerre and G. Humbert. We provide new criteria of algebraic rectifiability, relate this notion to quadratic differentials, and generalize it to differentials of higher order.

1. INTRODUCTION

1.1. Historical background. One of the fundamental problems in mathematics considered since the time of Archimedes and Apollonius is calculation of the length of an arc of a curve in two and three dimensions. In the 17-th century a great progress in this area has been achieved by such celebrities as E. Torricelli, J. Wallis, Ch. Wren, G. Leibniz, H. van Heuraut, P. de Fermat, see e.g. [10].

However there are not that many cases in which the arc length can be found explicitly and typically, for a (real) algebraic curve, its arc length does not depend algebraically on the endpoints of the arc. The fundamental example illustrating this phenomenon is the length of an arc of an ellipse whose study led to the development of the theory of elliptic functions by C. G. Jacobi. Apparently, historically first example of an algebraic curve whose arc length is an algebraic function of the endpoints is the semicubic parabola $y^2 = k^2 x^3$ where k is a fixed real number. It was discovered by W. Niele in mid 17-th century and provides one of the few explicit examples of calculation of the length of a curve in the undergraduate calculus course.

In the present paper we will mainly be interested in the notion of an *algebraically rectifiable curve* which is a (real) algebraic curve whose arc length is an algebraic function of the endpoints. It is not quite clear who actually introduced it, but G. Humbert [8] quotes J. A. Serret whose textbook "Cours d'algèbra supérieure" was very popular in the 1860's and later. E. Laguerre was definitely familiar with this notion and, in our opinion, it might as well be that I. Newton, G. Leibniz and L. Euler thought about this problem. In any case, Newton considered rather similar algebraically integrable curves, comp. [1].

The natural connection between the algebraic rectifiability and evolutes was discovered in [8]. (Originally, evolutes and involutes were in details studied by Ch. Huygens, see [9]. For the basic notions and results on evolutes see e.g. [7].) One of the fundamental results of [8], see p. 136, claims the following.

Proposition 1. *A plane algebraic curve is algebraically rectifiable if and only if it is the evolute of an algebraic curve.*

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Description of special classes of algebraically rectifiable curves can be found in [18].

1.2. Our results. The aim of this paper is to recast the classical problem of algebraic rectifiability in the language of meromorphic differentials on the normalization of an algebraic curve. To an algebraic plane curve Γ we attach the quadratic differential

$$ds^2 = dx^2 + dy^2$$

on its normalization. This elementary object records the algebraic behaviour of the Euclidean length element, and its divisor is controlled by isotropic tangencies and by the branches at infinity. In particular, for a generic rational curve of degree d the zero divisor has degree $4d - 4$, while the poles occur at the points at infinity, each with order four. This gives a useful bridge between classical projective geometry and the strata of meromorphic quadratic differentials.

A first contribution is an intrinsic realization criterion. Given a compact real Riemann surface (X, ρ) and a ρ -real quadratic differential q , we show that q is of the form $dx^2 + dy^2$ for a real meromorphic plane map if and only if it admits an exact admissible splitting

$$q = \omega \rho^* \bar{\omega}, \quad \omega = dz.$$

Thus the realization problem separates into a divisor-theoretic condition and a period condition. We also prove the corresponding uniqueness statement: once the splitting, equivalently the divisor of dz , is fixed, the realization is unique up to a direct Euclidean motion, and up to a Euclidean similarity if the differential is multiplied by a positive constant.

A second main point is the exactness criterion for higher order differentials. For a meromorphic k -differential ϕ on a compact Riemann surface, we prove that exactness of the canonical k -cover is equivalent to algebraicity of the Abelian integral $\int \phi^{1/k}$, and also to the representation

$$\phi = f \left(\frac{df}{f} \right)^k$$

for a meromorphic function f . This gives a convenient uniform language for rectifiability and for its affine analogue. In the quadratic case it recovers the algebraic arc-length condition.

We then relate this differential viewpoint to Humbert's classical theorem. We prove that for a non-linear plane algebraic curve the following conditions are equivalent: algebraic rectifiability, exactness of the canonical double cover of ds^2 , algebraicity of the involutes, and being the evolute of an algebraic curve. Thus Humbert's evolute criterion is precisely the geometric form of the exactness criterion for the arc-length quadratic differential.

The paper also contains several consequences and examples. We show that a non-linear rational real plane curve whose arc-length quadratic differential has only two singularities must be a circle, up to Euclidean similarity and reparametrization. We compute the corresponding differentials for conics, the Bernoulli lemniscate, the semicubic parabola and several rational examples, and locate them in the appropriate strata. Finally, we discuss the analogous construction in special affine geometry, where the Euclidean quadratic differential is replaced by the affine cubic differential

$(\gamma' \wedge \gamma'')dt^3$, and obtain the parallel exactness criterion for algebraic affine involutes. Conceptually, the paper studies when the Euclidean metric restricted to an algebraic curve becomes algebraically integrable.

Let us also mention several closely related modern developments. Farouki and Sakkalis proved that, except for straight lines, real rational curves cannot be parametrized by rational functions of arc length, and subsequently studied algebraically rectifiable parametric curves, including low-degree classifications and links with Pythagorean-hodograph curves [6, 18]. The latter theory has become a substantial subject in geometric design; see, for example, the survey [11] and the monograph [5]. More recently, Solynin and Solynin revisited the interpretation of real algebraic curves via meromorphic quadratic differentials, following the circle of ideas of Langer and Singer [13, 19].

The structure of this note is as follows. In Section 2, we introduce the arc length form and the associated quadratic differential and record their basic divisor properties. In Section 3 we study which quadratic differentials on a given Riemann surface can be realized as arc length differentials and how unique such a realization is. Section 4 discusses exact quadratic and higher order differentials, which provide a natural language for algebraic rectifiability. Section 5 provides characterizations of plane rectifiable algebraic curves. Section 6 gives examples, including conics, the Bernoulli lemniscate and semicubic parabolas. Section 7 sketches the analogous questions in affine differential geometry, and the appendix recalls the Plücker theorems used for generic curves and their evolutes.

2. ARC LENGTH 1-FORM AND QUADRATIC DIFFERENTIAL

The following notions appeared in different contexts and should be better known. We rediscovered them as well before finding relevant discussions in [13, 14, 15, 12]. The latter texts contain connections of these objects with foci, the Schwarz derivative, the matrix range, etc.

Definition 1. *For a plane algebraic curve $\Gamma \subset \mathbb{C}^2$ with the affine coordinates (x, y) given by the equation $P(x, y) = 0$, we define its **arc length 1-form** as:*

$$ds = \frac{\sqrt{(P'_x)^2 + (P'_y)^2}}{P'_y} dx$$

and we define its **arc length quadratic differential** as:

$$ds^2 := (ds)^{\otimes 2} = \frac{(P'_x)^2 + (P'_y)^2}{(P'_y)^2} dx^2.$$

Notation 1. *Given a plane algebraic curve $\Gamma \subset \mathbb{C}^2$, denote by $\bar{\Gamma} \subset \mathbb{C}P^2$ its projective closure and by $\tilde{\Gamma}$ the normalization of $\bar{\Gamma}$. Denote by $\Pi : \tilde{\Gamma} \rightarrow \bar{\Gamma} \subset \mathbb{C}P^2$ the map sending the normalization to the projective closure.*

Lemma 2. *In the above notation, the differential ds^2 is a well-defined meromorphic quadratic differential on the Riemann surface $\tilde{\Gamma}$. The differential ds^2 is the pullback of the standard meromorphic quadratic differential $dS^2 := dx^2 + dy^2$ defined on $\mathbb{C}P^2$ under the birational map Π .*

Proof. The assertion follows by computing the pullback of the Euclidean quadratic form along a local parametrization of the normalization. On the smooth affine locus, implicit differentiation gives $dy = -(P_x/P_y)dx$, hence

$$dx^2 + dy^2 = \frac{P_x^2 + P_y^2}{P_y^2} dx^2.$$

This expression is independent of the local affine chart and therefore extends meromorphically to the normalization. \square

Remark 1. *The number of poles of ds^2 minus the number of its zeros equals $2\chi(\tilde{\Gamma})$. (We count both poles and zeros with their multiplicities).*

Let us now describe the singular points of ds^2 . Denote by D_0 (resp. D^∞) the divisor of its zeros (resp. poles) on the normalization $\tilde{\Gamma}$.

We need the following classical definition (see short introduction in [16], [17] and further references therein). One can easily check that any circle in \mathbb{R}^2 (or \mathbb{C}^2) with coordinates (x, y) intersects the line at infinity at two points I and J given by $(1, i, 0)$ and $(1, -i, 0)$ respectively in the homogeneous coordinates $(X : Y : Z)$ such that $x = X/Z$ and $y = Y/Z$. (Here i is the imaginary unity).

The points I and J are called the *circular points at infinity*. Lines in $\mathbb{C}P^2 \supset \mathbb{C}^2$ passing through either I or J , and different from the line at infinity, are called *circular* or *isotropic lines*. In the 1830s generalizing the properties of foci of a quadric, J. Plücker introduced the notion of a *focus* of an arbitrary algebraic curve $\gamma \subset \mathbb{C}P^2$ as the intersection point of two tangents to γ one of which passes through I and another through J . If neither I nor J lie on γ , then its foci are called *ordinary* and their number (counting multiplicity) equals to the square of the class of γ . For a real curve γ , only class-many of its foci can be real, the remaining are complex. (See more details in [17].) A tangent line to γ passing through either I or J will be called *circular*. Denote by $\mathfrak{D}_\gamma \subset \gamma$ the divisor of all points of contact with γ of the circular tangent lines to γ . Typically, \mathfrak{D} consists of twice the class of γ smooth points of γ .

Notice that the tangent line is well-defined at each smooth point of γ . Lines passing through singular points of γ are called *tangent* if they represent points of the dual curve γ^* .

Proposition 3. *For a generic plane algebraic curve $\Gamma \subset \mathbb{C}^2$, the divisor D_0 of zeros of ds^2 coincides with the pullback $\Pi^{-1}(\mathfrak{D}_\Gamma)$ and the divisor D^∞ of poles of ds^2 coincides with $\Pi^{-1}(\Gamma^\infty)$ where Γ^∞ is the divisor of $\bar{\Gamma}$ at infinity. Thus, if Γ is a generic curve of degree d , then $|D_0| = 2d(d-1)$ and D^∞ consists of d distinct points with certain multiplicity, see below. For a generic rational curve Γ of degree d , $|D_0| = 4d-4$ and D^∞ consists of d distinct points where each pole has multiplicity 4.*

Proof. For a local parametrization $t \mapsto (x(t), y(t))$ of the normalization one has

$$ds^2 = (x'(t)^2 + y'(t)^2) dt^2.$$

Thus zeros occur exactly when the tangent direction is isotropic, i.e. when the tangent line passes through one of the circular points at infinity. For a generic curve all such contacts are simple, and their number equals twice the class of the curve. Poles occur at the points lying over the line at infinity. In the rational

generic case the class is $2d - 2$, giving $4d - 4$ zeros, and a local parameter at each of the d branches at infinity gives a pole of order 4. \square

Corollary 1. (i) For a generic Γ of degree d , the number of poles of ds^2 (with multiplicities) minus the number of zeros equals $4d - 2d(d - 1) = 2\chi(\Gamma) = 2(2 - 2g(\Gamma)) = 4 - 2(d - 1)(d - 2)$.

(ii) For a generic rational Γ of degree d , the number of poles of ds^2 (with multiplicities) minus the number of zeros equals $4d - (4d - 4) = 2\chi(\Gamma) = 4$.

Proof. Straightforward calculation. \square

3. WHICH QUADRATIC DIFFERENTIALS CAN BE INDUCED AS ARC LENGTH?

Given a compact Riemann surface X , we now ask which quadratic differentials on X can be induced as arc length differentials from $dS^2 = dx^2 + dy^2$ under birational realizations

$$\Pi : X \rightarrow \mathbb{C}P^2$$

of X as a plane algebraic curve. In this form the question has two parts: existence and uniqueness. The point of this subsection is that the correct object is not only the quadratic differential q , but also a splitting

$$q = \omega \eta$$

into two conjugate meromorphic 1-forms. In the plane one has

$$z = x + iy, \quad w = x - iy, \quad q = dx^2 + dy^2 = dz dw,$$

so the two factors are the pullbacks of the two isotropic differentials dz and dw .

We shall use the following terminology. Let X be equipped with an anti-holomorphic involution ρ , and let q be a non-zero meromorphic quadratic differential satisfying

$$\rho^* \bar{q} = q.$$

A divisor D on X will be called an admissible half-divisor for q if

$$D + \rho(D) = \text{div}(q).$$

An admissible half-divisor is called exact if there exists a meromorphic 1-form ω with

$$\text{div}(\omega) = D, \quad q = \omega \rho^* \bar{\omega},$$

and all periods of ω vanish. Equivalently, $\omega = dz$ for a meromorphic function z on X .

Theorem 4 (Existence criterion). *Let (X, ρ) be a compact real Riemann surface and let q be a non-zero ρ -real meromorphic quadratic differential on X . Then q is induced by a real meromorphic plane map*

$$X \rightarrow \mathbb{C}^2, \quad p \mapsto (x(p), y(p)),$$

in the sense that

$$q = dx^2 + dy^2,$$

if and only if q admits an exact admissible half-divisor. More explicitly, this means that there exists a meromorphic 1-form ω such that

$$q = \omega \rho^* \bar{\omega}$$

and ω has zero periods.

If $\omega = dz$, the corresponding real plane map is

$$x = \frac{1}{2}(z + \overline{z \circ \rho}), \quad y = \frac{1}{2i}(z - \overline{z \circ \rho}).$$

It is birational onto its image precisely when the two meromorphic functions x and y generate the full function field $\mathbb{C}(X)$.

Proof. Assume first that q comes from a real plane map. Put $z = x+iy$ and $w = x-iy$. Since the map is real with respect to ρ , one has $w = \overline{z \circ \rho}$. Therefore

$$q = dx^2 + dy^2 = dz dw = dz \rho^* \overline{dz}.$$

Thus $D = \text{div}(dz)$ is an admissible half-divisor. Moreover dz is exact, hence has zero periods.

Conversely, suppose that

$$q = \omega \rho^* \overline{\omega}$$

with ω exact. Choose a meromorphic primitive z of ω , so that $\omega = dz$, and set

$$w = \overline{z \circ \rho}, \quad x = \frac{z+w}{2}, \quad y = \frac{z-w}{2i}.$$

Then x and y are real meromorphic functions on X , and

$$dx^2 + dy^2 = dz dw = \omega \rho^* \overline{\omega} = q.$$

This proves existence of a real meromorphic plane map. Finally, a meromorphic map to the plane is birational onto its image exactly when its coordinate functions generate the function field of X ; otherwise the map factors through the intermediate curve with function field $\mathbb{C}(x, y)$. \square

Remark 2. *The theorem separates the two obstructions to existence. The first is a divisor-theoretic obstruction: the divisor of q has to split as $D + \rho(D)$. In particular, at a fixed point of ρ all orders in $\text{div}(q)$ must be even. The second is a period obstruction: the corresponding meromorphic 1-form ω must be exact. The latter condition includes, in particular, vanishing of all residues at the poles of ω .*

Proposition 5 (Uniqueness for a fixed splitting). *Let q be as in Theorem 4. Suppose that two real meromorphic maps*

$$z_j = x_j + iy_j, \quad w_j = x_j - iy_j, \quad j = 1, 2,$$

induce the same quadratic differential

$$q = dz_1 dw_1 = dz_2 dw_2,$$

where $w_j = \overline{z_j \circ \rho}$. If

$$\text{div}(dz_1) = \text{div}(dz_2),$$

then the two realizations differ by a direct Euclidean motion. More precisely, there exist $\theta \in \mathbb{R}$ and $c \in \mathbb{C}$ such that

$$z_2 = e^{i\theta} z_1 + c.$$

If the induced quadratic differentials are proportional by a positive constant, then the conclusion is the same with a Euclidean similarity in place of a Euclidean motion.

Proof. The quotient dz_2/dz_1 is a nowhere vanishing meromorphic function on the compact Riemann surface X , hence is constant. Thus

$$dz_2 = \lambda dz_1$$

for some $\lambda \in \mathbb{C}^*$. The reality condition gives $dw_2 = \bar{\lambda} dw_1$. Since the quadratic differentials are equal,

$$dz_2 dw_2 = |\lambda|^2 dz_1 dw_1 = dz_1 dw_1,$$

so $|\lambda| = 1$. Hence $\lambda = e^{i\theta}$, and integration gives $z_2 = e^{i\theta} z_1 + c$. The proportional case is identical and gives $|\lambda|$ equal to the similarity ratio. \square

Corollary 2. *For a fixed pair (X, q) satisfying the hypotheses above, the realizations of q are classified, up to direct Euclidean motions, by exact admissible half-divisors D such that the associated primitive z gives $\mathbb{C}(x, y) = \mathbb{C}(X)$. In particular, for fixed q there are only finitely many possible divisor splittings, and for each such splitting there is at most one realization modulo direct Euclidean motions.*

Proof. Every realization gives the divisor $D = \text{div}(dz)$, and this D is an exact admissible half-divisor by Theorem 4. Conversely, every exact admissible half-divisor gives a real meromorphic plane map. Proposition 5 shows uniqueness for a fixed D . Since the support and multiplicities of $\text{div}(q)$ are finite, there are only finitely many decompositions $D + \rho(D) = \text{div}(q)$. \square

Lemma 6. *Let p be a smooth point of Γ , and assume that a line through one of the circular points at infinity has ordinary tangency with Γ at p . Then the corresponding zero of the arc length quadratic differential ds^2 is simple. Moreover, at a generic branch of Γ at infinity, the local square root ds has a pole of order 2 with zero residue; hence ds^2 has a pole of order 4.*

Proof. Let t be a local parameter at a smooth affine point and write

$$ds^2 = (x'(t)^2 + y'(t)^2) dt^2.$$

The equation $x'(t)^2 + y'(t)^2 = 0$ says exactly that the tangent direction is isotropic, or equivalently that the tangent line passes through one of the circular points at infinity. Ordinary contact with the corresponding isotropic tangent is therefore equivalent to a simple zero of the factor $x'(t)^2 + y'(t)^2$.

At a generic branch at infinity choose a parameter u such that

$$x = \frac{a}{u} + O(1), \quad y = \frac{b}{u} + O(1),$$

with $a^2 + b^2 \neq 0$. Then

$$dx^2 + dy^2 = (a^2 + b^2) \frac{du^2}{u^4} + O\left(\frac{du^2}{u^3}\right).$$

Thus a local square root has the form

$$ds = \frac{c du}{u^2} + O(1) du, \quad c^2 = a^2 + b^2.$$

There is no du/u term, so the residue is zero. The asserted pole orders follow. \square

Let us also spell out the rational case. A rational curve $\Gamma \subset \mathbb{C}P^2$ is given by a triple of polynomials $(U(t), V(t), W(t))$ without a common factor. If

$$x(t) = \frac{U(t)}{W(t)}, \quad y(t) = \frac{V(t)}{W(t)},$$

then

$$ds^2 = ((x'(t))^2 + (y'(t))^2) dt^2 = \frac{(U'W - UW')^2 + (V'W - VW')^2}{W^4} dt^2.$$

Thus, in genus zero, the existence problem becomes the problem of deciding when a prescribed rational quadratic differential admits a representation of this Wronskian form. The criterion above gives a complementary intrinsic formulation: one has to choose a factor dz of q with zero residues and zero periods, and then integrate it to recover the rational function $z = x + iy$.

4. EXACT QUADRATIC AND HIGHER ORDER DIFFERENTIALS

For $k \geq 2$, a meromorphic k -differential on a Riemann surface X is a meromorphic section of the line bundle $K_X^{\otimes k}$ where K_X is the canonical line bundle. In local charts, a k -differential writes as $f(z)dz^k$ where f is a meromorphic function. The case $k = 2$ corresponds to quadratic differentials.

The moduli space of k -differentials is stratified according to the multiplicity of the zeros and the poles, see [2] for background. We denote by $\Omega^k \mathcal{M}_g(a_1, \dots, a_n)$ the moduli space of pairs (X, ω) where X is a compact Riemann surface of genus g and ω is a k -differential on X with n singularities of multiplicities a_1, \dots, a_n (up to a biholomorphic change of variable). Riemann-Roch theorem implies that $\sum_{i=1}^n a_i = k(2g - 2)$.

Definition 2. For a (meromorphic) k -differential ϕ on a compact Riemann surface X , the canonical k -cover $\Theta : X' \rightarrow X$ is a cover of degree k ramified at the singularities of ϕ whose order is not divisible by k and such that the pullbacks of each of the k branches of $\phi^{1/k}$ agree as a uni-valued 1-form. If the k -differential ϕ is primitive (if it is not the global power of a differential of lower order), its canonical k -cover is connected. The canonical k -cover is obtained by continuation of any branch of $\phi^{1/k}$ on X . (The canonical 1-form on X' will be denoted by $\sqrt[k]{\phi}$.)

In particular, for a meromorphic quadratic differential Ψ on a compact Riemann surface X , one gets a canonical double cover $\Theta : X' \rightarrow X$ branched at the singularities of Ψ of odd order and a meromorphic 1-differential $\sqrt{\Psi}$ on X' .

Definition 3. A meromorphic k -differential ϕ on a compact Riemann surface X is called exact if the 1-form $\sqrt[k]{\phi}$ is exact.

Theorem 7. For a meromorphic k -differential ϕ on a compact Riemann surface X , the following three conditions are equivalent:

- (1) the canonical 1-form $\sqrt[k]{\phi}$ is exact on the canonical k -cover X' ;
- (2) the Abelian integral $\int \phi^{1/k}$ is an algebraic multivalued function on X ;
- (3) there exists a meromorphic function f on X such that

$$\phi = f \left(\frac{df}{f} \right)^k.$$

Proof. If (3) holds, then on the canonical cover one may choose a branch of $f^{1/k}$ and write

$$\sqrt[k]{\phi} = f^{1/k} \frac{df}{f} = k d(f^{1/k}),$$

so the canonical 1-form is exact. This proves (3) \Rightarrow (1), and (1) \Rightarrow (2) is immediate: an exact primitive on the finite cover descends to a finite-valued, hence algebraic, multivalued function on X .

Conversely, if $\int \phi^{1/k}$ is algebraic, its continuation has only finitely many branches. Therefore the periods of the canonical form on X' vanish; otherwise continuation along powers of a loop with nonzero period would produce infinitely many values. Thus (ii) \Rightarrow (i).

Assume (i), and write $\sqrt[k]{\phi} = dg$ on X' . The deck group acts on dg by multiplication by k -th roots of unity. After adding a constant to g , the same is true for g itself. Hence $h = g^k$ is invariant under the deck group and descends to a meromorphic function on X . Since

$$dh = kg^{k-1} dg,$$

one obtains

$$\phi = (dg)^k = \frac{1}{k^k} h \left(\frac{dh}{h} \right)^k.$$

Absorbing the constant $1/k^k$ into h gives (3). \square

It should be remarked that any such k -differential with exact cover induces a conical metric of constant positive curvature with coaxial monodromy (by considering the logarithmic derivative of the developing map).

Corollary 1. *A singularity of such a k -differential ϕ either coincides with a singularity of f or a zero of df . More precisely, if z is a singularity of order a of f , then it is a singularity of order $a - k$ of ϕ . If z is not a singularity of f but is a zero of order a of df , then it is a zero of order ak of ϕ .*

In particular, singularities of ϕ whose order is at least $1-k$ and fails to be divisible by k are always zeros of f .

It is also true that if ϕ has only one pole and is defined on the Riemann sphere (in other words, ϕ is a polynomial), then f has no pole except the unique pole of ϕ and is therefore also a polynomial.

Remark 3. *The latter corollary implies in particular that the only degrees of freedom are the critical values of f (positions of the zeros of the k -differential whose order is a multiple of k in the developing map).*

Theorem 7 provides a parametrization of k -differentials with exact cover on a given compact Riemann surface.

Proposition 8. *Let ϕ be a meromorphic k -differential with exact canonical cover on a compact Riemann surface X . Assume that ϕ has no zero whose order is divisible by k . Then $X \simeq \mathbb{CP}^1$ and, in a suitable coordinate z ,*

$$\phi = \lambda z^a dz^k, \quad \lambda \in \mathbb{C}^*, \quad a \in \mathbb{Z}.$$

Proof. By Theorem 7, there is a meromorphic function $f : X \rightarrow \mathbb{CP}^1$ such that

$$\phi = f \left(\frac{df}{f} \right)^k.$$

If p is a critical point of f with $f(p) \neq 0, \infty$ and ramification order $r \geq 1$, then df has a zero of order r at p , and therefore ϕ has a zero of order kr , divisible by k . By assumption there are no such points. Hence all ramification of f lies over 0 and ∞ .

Thus f restricts to an unramified covering

$$X \setminus f^{-1}(\{0, \infty\}) \longrightarrow \mathbb{C}^*.$$

Equivalently, after compactification, f is a finite covering of \mathbb{CP}^1 ramified over at most the two points 0 and ∞ . By the Riemann–Hurwitz formula this forces $X \simeq \mathbb{CP}^1$, and after choosing a coordinate z on X one may write $f = z^n$ up to multiplication by a non-zero constant and replacement of z by $1/z$. Consequently

$$\phi = z^n \left(n \frac{dz}{z} \right)^k = n^k z^{n-k} dz^k,$$

up to a non-zero constant. This is the claimed form. \square

Proposition 9. *Let Γ be a rational plane curve parametrized by two real rational functions $x(t)$ and $y(t)$, and let*

$$q = (x'(t)^2 + y'(t)^2) dt^2$$

be its arc length quadratic differential on \mathbb{CP}^1 . Then the divisor of q is invariant under complex conjugation and every real zero or pole of q has even order. Equivalently, after multiplication by a non-zero real constant, the coefficient of q factors as

$$\prod_i (t - \alpha_i)^{2a_i} \prod_j (t^2 - 2u_j t + u_j^2 + v_j^2)^{b_j},$$

where $\alpha_i, u_j, v_j \in \mathbb{R}$, $v_j \neq 0$, and the exponents a_i, b_j are integers. In particular, the non-real singularities occur in conjugate pairs, whereas real singularities occur with even order.

Proof. Set $z(t) = x(t) + iy(t)$ and $w(t) = x(t) - iy(t)$. Then $w(t) = \overline{z(t)}$ and

$$q = dz dw.$$

Thus the orders of dw are obtained from the orders of dz by complex conjugation. Hence the divisor of q is conjugation invariant. If $t = \alpha$ is real, the orders of dz and dw at α coincide, so

$$\text{ord}_\alpha(q) = 2 \text{ord}_\alpha(dz).$$

This proves the parity statement. The displayed factorization is just the standard factorization of a real rational function into real linear factors and irreducible real quadratic factors corresponding to non-real conjugate pairs. \square

Quadratic differentials corresponding to straight lines give the flat structure of the usual flat plane, with a unique pole of order four and no other singularities. The following elementary criterion is the form used later.

Proposition 10. *Let Γ be a rational plane curve parametrized by two real rational functions $x(t)$ and $y(t)$, and put $z = x + iy$. Assume that the arc length quadratic differential belongs to $\Omega^2 \mathcal{M}_0(-4)$ and that dz has no non-real pole which is cancelled in the product $q = dz d\bar{z}$. Then Γ is a straight line.*

Proof. After a real Möbius change of parameter, the unique pole of q is at $t = \infty$. By the hypothesis on cancellations, dz has no finite pole. Hence z is a polynomial. Since q has a pole of order four at infinity, dz has a pole of order two at infinity, so z has degree one. Therefore x and y are affine functions of the real parameter, and the image is a straight line. \square

Remark 4.1. A tempting strengthening would be to characterize rational curves whose arc length differential has only real singularities. In this generality one has to control possible cancellations between dz and $dw = d\bar{z}$ at non-real points. The clean statement used below is the following sufficient criterion: if, after normalization, all singularities of dz itself lie on the real locus, then $dz = \lambda R(t)dt$ with R real rational and $\lambda \in \mathbb{C}^*$; hence $x'(t)$ and $y'(t)$ are real constant multiples of the same rational function and the image is a line.

Lemma 11. *Let X be a real algebraic curve with anti-holomorphic involution $p \mapsto \bar{p}$, and let x, y be real meromorphic functions on X . Put*

$$z = x + iy, \quad w = x - iy,$$

so that $w(p) = \overline{z(\bar{p})}$, and let $q = dx^2 + dy^2 = dz dw$. Then the divisor of q is invariant under the real structure. At a real point p , the order of q is twice the order of dz ; in particular every real singularity of q has even order.

Proof. The relation $w(p) = \overline{z(\bar{p})}$ implies that the orders of dw are obtained from those of dz by conjugation. Since $q = dz dw$, the divisor of q is invariant under conjugation. If p is real, then dz and dw have the same order at p , so

$$\text{ord}_p(q) = \text{ord}_p(dz) + \text{ord}_p(dw) = 2 \text{ord}_p(dz).$$

This proves the claim. \square

5. CHARACTERIZATION OF PLANE RECTIFIABLE CURVES

The evolute of a planar curve is formed by the centers of its osculating circles. It is equivalently defined as the envelope of the normals of the curve (normal to the tangent line for the Euclidean structure). The following result reformulates Humbert's theorem in the language of the arc length quadratic differential.

Theorem 12. *Let X be an irreducible algebraic plane curve and let \tilde{X} be its normalization. Assume that X is not a line and work away from isotropic tangent directions and from the exceptional points where the usual evolute-involute correspondence degenerates. Let*

$$q = dx^2 + dy^2$$

be the arc length quadratic differential on \tilde{X} . Then the following conditions are equivalent:

- (1) X is algebraically rectifiable, i.e. the arc length integral

$$S = \int \sqrt{q}$$

is an algebraic multivalued function on X ;

- (2) *the canonical double cover of q is exact;*
- (3) *one, equivalently every, non-constant involute of X is an algebraic curve;*
- (4) *X is the evolute of an algebraic curve.*

Proof. Let $r = (x, y)$ be a local parametrization of X on the normalization, and let S be a local primitive of the arc length form, so that $dS^2 = q$. On the canonical double cover of q the unit tangent vector

$$T = \frac{dr}{dS} = \left(\frac{dx}{dS}, \frac{dy}{dS} \right)$$

has meromorphic coordinates. A local involute of X is given by

$$I_C = r - (S + C)T,$$

where C is a constant. If S is algebraic, then all coordinates of all involutes are algebraic. Conversely, suppose that one non-constant involute I_C is algebraic. Since r and T are algebraic on the canonical cover, the vector $(S+C)T = r - I_C$ is algebraic. Away from the isolated points where T is undefined or zero, at least one coordinate of T is non-zero; division by that coordinate shows that $S + C$, and therefore S , is algebraic. Thus algebraic rectifiability is equivalent to the algebraicity of one, or equivalently all, non-constant involutes.

By Theorem 7 with $k = 2$, algebraicity of the Abelian integral $S = \int \sqrt{q}$ is equivalent to exactness of the canonical one-form on the canonical double cover of q . This proves the equivalence of (1), (2), and (3).

Finally, outside the standard exceptional locus, the evolute of an involute of X is X itself. Conversely, if X is the evolute of an algebraic curve Y , then Y is locally an involute of X . Hence the algebraicity of an involute is equivalent to saying that X is the evolute of an algebraic curve. This is Humbert's geometric characterization. \square

Remark 4. Thus Theorem 12 is the differential-theoretic form of Humbert's theorem quoted in Proposition 1. Humbert's formulation uses evolutes, while the present formulation uses the canonical cover of the quadratic differential $q = dx^2 + dy^2$. The two viewpoints are equivalent because passing from a curve to its involutes amounts exactly to integrating the arc length form.

Using our previous results, we describe algebraically rectifiable rational curves. (Our result generalizes the very special case settled in [18]). We need to answer the question for which $R_1 = U/W$ and $R_2 = V/W$ there exists a rational function $f = P/Q$ such that

$$(R'_1)^2 + (R'_2)^2 = (f')^2/f.$$

Theorem 13. *Let $\gamma : \mathbb{CP}^1 \rightarrow \mathbb{CP}^2$ be a non-constant rational real plane curve, and let*

$$q = dx^2 + dy^2$$

be its Euclidean arc length quadratic differential on the normalization. Assume that q has exactly two singularities. If the image of γ is not a line, then it is a circle. More precisely, after a real Möbius change of parameter and a Euclidean similarity, the complex coordinate $z = x + iy$ has the form

$$z(t) = z_0 + c \left(\frac{t+i}{t-i} \right)^m,$$

where $c \neq 0$ and $m \neq 0$ is an integer. In particular, if the parametrization is birational onto its image, then $|m| = 1$.

Proof. Put

$$z = x + iy, \quad w = x - iy.$$

Then $q = dz dw$, and $w(t) = \overline{z(t)}$. In particular, the divisor of q is invariant under the real structure on the parameter sphere.

We first discuss the case in which the two singularities are real. After a real Möbius change of parameter, they are 0 and ∞ . Since, at a real point, dz and dw have the same order, the orders of q at both singularities are even. Thus

$$q = Ct^{2a} dt^2$$

for some integer a and some $C \neq 0$. Correspondingly, $dz = \lambda t^a dt$ after changing the non-zero constant λ . If $a = -1$, then z has a logarithmic term, impossible for a rational parametrization. If $a \neq -1$, then

$$z = z_0 + ct^{a+1}.$$

Since $w = \overline{z(t)}$, the real parametrization is contained in the real affine line determined by the complex direction c . Hence in the real case the image is a line.

It remains to consider the case in which the two singularities are non-real conjugate points. Since the divisor of a quadratic differential on \mathbb{CP}^1 has degree -4 , the two conjugate singularities have the same order and therefore both are double poles. After a real Möbius change of parameter, they are i and $-i$, and

$$q = C \frac{dt^2}{(t^2 + 1)^2}$$

for some $C \neq 0$. Since $q = dz dw$, there is an integer a and non-zero constants λ, μ such that

$$dz = \lambda \frac{(t+i)^a}{(t-i)^{a+2}} dt, \quad dw = \mu \frac{(t-i)^a}{(t+i)^{a+2}} dt.$$

Set

$$s = \frac{t+i}{t-i}.$$

Then s maps the real line to the unit circle and

$$dz = -\frac{\lambda}{2i} s^a ds.$$

The case $a = -1$ would give a logarithm, so it is impossible for a rational parametrization. Therefore

$$z = z_0 - \frac{\lambda}{2i(a+1)} s^{a+1}.$$

For real t one has $|s| = 1$, so the image is contained in a Euclidean circle. Since the curve is irreducible and non-constant, its image is this circle. Taking $m = a + 1$ gives the asserted normal form. Finally, a birational parametrization of the circle has degree one, so $|m| = 1$. \square

The simplest quadratic differentials with exact cover are of the form $\lambda t^a dt^2$. Such differentials can be obtained as arc length quadratic differentials of some plane curve only in the case $a = 0$ and $a = -2$. This defines respectively the straight line and the circle. In the second case, the quadratic differential does not have exact cover.

6. EXAMPLES

The examples below are meant to illustrate distinct phenomena rather than to provide a long catalogue. Conics give the first non-trivial strata of the arc-length quadratic differential; the Bernoulli lemniscate gives a finite-area “pillowcase” differential; the semicubic parabola gives a classical rectifiable singular curve; and the last two rational examples show, respectively, a higher degree Pythagorean-hodograph curve and a more generic rational curve with several simple zeros of the length differential.

6.1. Conics. Let $X \simeq \mathbb{C}\mathbb{P}^1$ be a non-degenerate conic, parametrized by two meromorphic functions f and g . The Euclidean arc-length quadratic differential on the normalization is

$$q = df^2 + dg^2.$$

For a general conic this differential is not exact on its canonical double cover; the circle is the exceptional rectifiable case.

6.1.1. Hyperbolas. Put

$$f(t) = a \frac{1+t^2}{2t}, \quad g(t) = b \frac{1-t^2}{2t}.$$

Then $(f/a)^2 - (g/b)^2 = 1$, and

$$q = \frac{a^2(t^2-1)^2 + b^2(t^2+1)^2}{4t^4} dt^2.$$

Thus q has poles of order four at 0 and ∞ . Its zeros are the four simple roots of

$$t^4 + 2 \frac{b^2 - a^2}{a^2 + b^2} t^2 + 1 = 0,$$

namely

$$t = \pm \frac{a+bi}{\sqrt{a^2+b^2}}, \quad t = \pm \frac{a-bi}{\sqrt{a^2+b^2}}.$$

Consequently a non-circular hyperbola belongs to $\Omega^2 \mathcal{M}_0(1, 1, 1, 1, -4, -4)$.

6.1.2. Ellipses. Parametrize an ellipse by

$$f(t) = a \frac{2t}{1+t^2}, \quad g(t) = b \frac{1-t^2}{1+t^2}.$$

Then $(f/a)^2 + (g/b)^2 = 1$, and

$$q = \frac{4a^2(1-t^2)^2 + 16b^2t^2}{(1+t^2)^4} dt^2.$$

If $a = b$, the ellipse is a circle and

$$q = \frac{4a^2}{(1+t^2)^2} dt^2 = \left(\frac{2a}{1+t^2} dt \right)^2.$$

It belongs to $\Omega^2 \mathcal{M}_0(-2, -2)$. The square root has non-zero periods around the two poles, so the corresponding arc-length integral is logarithmic on the complex normalization, although the real circle has the expected elementary length parameter.

If $a \neq b$, then q has two poles of order four at $t = \pm i$. Its zeros are the roots of

$$t^4 + \frac{4b^2 - 2a^2}{a^2} t^2 + 1 = 0.$$

For a non-circular ellipse these four roots are simple, and the differential again lies in $\Omega^2\mathcal{M}_0(1, 1, 1, 1, -4, -4)$.

6.1.3. *Parabolas.* For the parabola $f^2 = ag$ we use the parametrization

$$f(t) = t, \quad g(t) = \frac{t^2}{a}.$$

Then

$$q = \frac{4t^2 + a^2}{a^2} dt^2.$$

It has two simple zeros at $t = \pm ai/2$ and one pole of order six at infinity; hence it belongs to $\Omega^2\mathcal{M}_0(1, 1, -6)$.

6.2. Rational curves beyond conics.

6.2.1. *The Bernoulli lemniscate.* The Bernoulli lemniscate

$$(x^2 + y^2)^2 = x^2 - y^2$$

is parametrized by

$$x(t) = \frac{t + t^3}{1 + t^4}, \quad y(t) = \frac{t - t^3}{1 + t^4}.$$

A direct calculation gives

$$q = dx^2 + dy^2 = \frac{2}{t^4 + 1} dt^2.$$

Thus q has four simple poles and no zeros; it belongs to $\Omega^2\mathcal{M}_0(-1, -1, -1, -1)$. The associated flat surface is the standard pillowcase-type surface.

6.2.2. *The semicubic parabola.* The semicubic parabola

$$ay^2 = x^3$$

is parametrized by

$$x(t) = at^2, \quad y(t) = at^3.$$

Its arc-length quadratic differential is

$$q = a^2 t^2 (4 + 9t^2) dt^2.$$

It belongs to $\Omega^2\mathcal{M}_0(2, 1, 1, -8)$. Moreover q is exact in the sense of Theorem 7, since

$$q = f \left(\frac{df}{f} \right)^2, \quad f(t) = \frac{a^2}{2916} (4 + 9t^2)^3.$$

This is the classical singular algebraically rectifiable example.

6.2.3. *A Pythagorean-hodograph quintic.* Let

$$u(t) = t^2 - 1, \quad v(t) = 2t,$$

and define a real polynomial curve by

$$x'(t) = u(t)^2 - v(t)^2 = t^4 - 6t^2 + 1, \quad y'(t) = 2u(t)v(t) = 4t^3 - 4t.$$

After integration one obtains

$$x(t) = \frac{t^5}{5} - 2t^3 + t, \quad y(t) = t^4 - 2t^2.$$

Then

$$q = dx^2 + dy^2 = (u^2 + v^2)^2 dt^2 = (t^2 + 1)^4 dt^2.$$

Thus the curve is algebraically rectifiable: the arc length form is $(t^2 + 1)^2 dt$, whose primitive is rational. The differential belongs to

$$\Omega^2 \mathcal{M}_0(4, 4, -12),$$

with zeros of order four at $t = \pm i$ and a pole of order twelve at infinity. This example is useful because it is smooth as a parametrized polynomial curve and rectifiable for a reason different from the elementary semicubic parabola: it comes from a non-linear Pythagorean-hodograph identity.

6.2.4. *A rational curve with many zeros.* Consider the rational curve

$$x(t) = \frac{t^3}{(t^2 + 1)^2}, \quad y(t) = \frac{3t^2 + 1}{(t^2 + 1)^2}.$$

A direct calculation gives

$$q = \frac{t^2(t^6 + 30t^4 - 15t^2 + 4)}{(t^2 + 1)^6} dt^2.$$

The points $t = \pm i$ are poles of order six, $t = 0$ is a zero of order two, and, provided the sextic factor has simple roots, the remaining six zeros are simple. Hence this example lies in

$$\Omega^2 \mathcal{M}_0(2, 1, 1, 1, 1, 1, 1, -6, -6).$$

It is included to show the more typical behaviour of rational plane curves: the length differential may have several zeros and poles and need not be the square of a rational one-form.

7. AFFINE DIFFERENTIAL GEOMETRY OF PLANE CURVES AND AFFINE EVOLUTE

In Euclidean geometry, the osculating circle at a point of a plane curve is the unique circle making second order contact (limit of the circle passing through three infinitesimally close points). This definition can be extended to more general objects of affine geometry.

Definition 4. *For a point x of a plane curve Γ , the hyperosculating parabola of Γ at x is the unique parabola making third order contact with Γ at x . Similarly, the hyperosculating conic of Γ at x is the unique conic making fourth order contact.*

7.1. Hyperosculating parabola. For a curve Γ , between any pair of points x and y , there is a triangle whose vertices are x , y and the intersection of the tangent lines of Γ at x and y . The area of this triangle is invariant by the action of the special-affine group.

There is a unique parabola passing through x and y with the same tangent lines as Γ at these two points. This provides an equivalent definition of hyperosculating parabola.

Infinitesimally close points x and y define an infinitesimal triangle whose area is a special-affine local invariant. For this purpose, curve Γ can be locally identified with its hyperosculating parabola.

For a parabola parametrized by $\gamma(t)$, the exterior product $\gamma'(t) \wedge \gamma''(t)$ is constant to a bivector A (moment of a central force in classical mechanics). The area of the triangle drawn by two points of parameters t_1 and t_2 is (after some calculations) $\frac{(t_2-t_1)^3 A}{8}$.

As a consequence, the third root of this area is additive for parameter t and can serve as an affine arc length on the parabola.

By identifying locally any smooth curve with its hyperosculating parabola, we get an arc length function by integrating the third root of $\gamma'(t) \wedge \gamma''(t) dt^3$. Just like the Euclidean structure of the plane induces a quadratic differential, the special-affine structure of the plane induces a cubic differential.

The cubic differential induced by the special-affine structure is an invariant of a plane embedding. As in the Euclidean case, however, one should not claim uniqueness of the embedding from this differential alone without specifying the appropriate affine curvature data. We therefore use the cubic differential below as a computable invariant rather than as a complete invariant.

7.2. Affine evolute. At every point x of a planar curve Γ , the direction of the *affine normal line* to Γ at x is the direction of the directrix of the hyperosculating parabola of Γ at x .

Definition 5. *The affine evolute of a smooth plane curve Γ is the envelope of its affine normal lines. Equivalently, in the classical affine differential geometry formulation, it is the curve traced by the centers of the hyperosculating conics of Γ .*

The center of a conic is a well-defined affine notion. For an ellipse it is the intersection point of any diameter. For an hyperbola it is the intersection of the two asymptotic lines.

Example 1. *The affine evolute of any ellipse or hyperbola is its center. The affine evolute of a parabola is a point at infinity.*

The first interesting cases begin with a cubic curve.

Proposition 14. *The affine evolute of an algebraic plane curve is algebraic, wherever it is defined.*

Proof. On the normalization of the curve, the affine tangent, affine normal, and the center of the hyperosculating conic are obtained from a finite jet of a rational parametrization by algebraic operations and differentiation. Hence the corresponding point of the affine evolute is given by rational functions on the normalization, away from the exceptional locus where the affine normal construction degenerates. The image of a rational map from an algebraic curve is algebraic. \square

In both cases, the vector between a point of the evolute and the corresponding point of an involute is colinear to the tangent vector. Therefore, this correspondence is birational if and only some quantity is rational. This quantity is the ratio between the arc length and a square root.

7.3. Cubic differential for rational parametrizations. For a real algebraic curve parametrized by $OM(t) = (f(t), g(t))$, cubic differential $OM'(t) \wedge OM''(t) dt^3$ is a special affine invariant, see [3].

For straight lines, the cubic differential is zero.

For a parabola, the cubic differential is adt^3 . It has a unique pole of order six.

For an ellipse parametrized by $f(t) = a \frac{2t}{1+t^2}$ and $g(t) = b \frac{1-t^2}{1+t^2}$, the cubic differential is $\frac{-8ab}{(1+t^2)^3} dt^3$. The associated flat surface is an infinite cylinder, just like the flat surface associated by the quadratic differential induced on the circle by the ambient Euclidean structure.

For a hyperbola parametrized by $f(t) = a \frac{1+t^2}{2t}$ and $g(t) = b \frac{1-t^2}{2t}$, the cubic differential is $\frac{ab}{t^3} dt^3$. The associated flat surface is also an infinite cylinder. It is the same as the ellipse up to a rotation.

For the semicubic parabola parametrized by $f(t) = at^2$ and $g(t) = at^3$, cubic differential is $6a^2t^2 dt^3$. It is far simpler than the quadratic differential of Euclidean geometry. It is a cubic differential with a zero of order two and a pole of order eight. In particular, it has exact cover.

Proposition 15. *Let X be the normalization of a non-linear real algebraic plane curve and let*

$$\Phi = (\gamma'(t) \wedge \gamma''(t)) dt^3$$

be the cubic differential induced by the special-affine structure of the plane. Assume that the affine involutes are understood in the classical special-affine sense on the open set where the affine normal construction is non-degenerate. Then the affine involutes are algebraic if and only if the cubic differential Φ has exact canonical cover.

Proof. On the smooth non-degenerate locus, the affine arc length is obtained by integrating a local branch of $\Phi^{1/3}$. The affine normal, affine evolute and corresponding affine involutes are obtained from a finite jet of the parametrization by algebraic operations, except for this affine arc length parameter. Therefore the coordinates of the affine involutes are algebraic over the function field of X precisely when the Abelian integral

$$\int \Phi^{1/3}$$

is an algebraic multivalued function on X .

By Theorem 7, applied with $k = 3$, this condition is equivalent to exactness of the canonical one-form on the canonical cubic cover of X associated with Φ . \square

Example 2. *Bernoulli lemniscate, defined by equation $(x^2 + y^2)^2 = x^2 - y^2$ is parametrized by $x(t) = \frac{t+t^3}{1+t^4}$ and $y(t) = \frac{t-t^3}{1+t^4}$. The arc length quadratic differential simplifies to $\frac{2dt^2}{t^4+1}$. This is an example of pillowcase flat surface. It belongs to $\Omega^2 \mathcal{M}_0(-1, -1, -1, -1)$.*

From an affine point of view, the cubic differential simplifies to $\frac{-12t dt^3}{(t^4+1)^2}$. Such cubic differential belongs to $\Omega^3 \mathcal{M}_0(1, 1, -2, -2, -2, -2)$. Zero and infinity are simple

zeros while the fourth roots of -1 are double poles. The associated flat surface has finite area.

Example 3. Singular cubic curve, defined by equation $y^2 = x^2 + x^3$ is parametrized by $x(t) = t^2 - 1$ and $y(t) = t^3 - t$. The arc length quadratic differential is $(9t^4 - 2t^2 + 1)dt^2$. It belongs to $\Omega^2\mathcal{M}_0(1, 1, 1, 1, -8)$.

From an affine point of view, the cubic differential is $(6t^2 + 1)dt^3$. Such cubic differential belongs to $\Omega^3\mathcal{M}_0(1, 1, -8)$.

Example 4. For any real rational function R , real algebraic curve defined by equation $y = R(x)$ is parametrized by $x(t) = t$ and $y(t) = R(t)$. The arc length quadratic differential is $(1 + R'^2)dt^2$. However, the affine cubic differential is $R''(t)dt^3$. Any second derivative of a real rational function can appear in that way. In particular, for a generic rational function R , zeros of the cubic differential are simple and its poles are of order three (with nonzero cubical residues).

8. APPENDIX. PLÜCKER FORMULAS FOR GENERIC (RATIONAL) CURVES AND THEIR EVOLUTES

The next information is either standard or can be easily derived from the results of Theorem 54 of [4].

Lemma 16. (1) A generic plane projective curve $\gamma \subset \mathbb{C}P^2$ of degree d has genus $\binom{d-1}{2}$, class $d' = d(d-1)$ (i.e. the degree of the dual curve $\gamma^* \subset (\mathbb{C}P^2)^*$) and $\#_i = 3d(d-2)$ inflection points. The dual curve γ^* has $\#'_{cusps} = 3d(d-2)$ cusps, no inflection points and $\#'_{nodes} = \binom{d(d-1)-1}{2} - \binom{d-1}{2}$ nodes.

(2) A generic plane rational projective curve $\gamma \subset \mathbb{C}P^2$ of degree d is nodal with $\#_{nodes} = \binom{d-1}{2}$ nodes and $\#_i = 3(d-2)$ inflection points. The class d' of such curve equals $2d-2$. The dual curve γ^* has $\#'_{cusps} = 3(d-2)$ cusps, no inflection points and $\#'_{nodes} = 2(d-2)(d-3)$ nodes.

Proof. Item (1) is standard. To settle item (2), notice that a generic plane rational curve γ of degree d is nodal, this is a standard genericity statement. Since the genus of γ is 0 its number of nodes equals its expected genus which for a curve of degree d equals $\binom{d-1}{2}$. The number $\#_i$ of inflection points of γ equals the expected number of inflection points minus $6\#_{nodes}$. The expected number of inflection points equals $3d(d-2)$. Thus $\#_i$ of γ equals $3d(d-2) - 3(d-1)(d-2) = 3d-6$. Furthermore, for a plane curve of degree d with cusps and nodes only, its class d' equals $d(d-1) - 2\#_{nodes} - 3\#_{cusps}$. Therefore in our case, $d' = d(d-1) - (d-1)(d-2) = 2d-2$. Since a generic rational curve γ has no cusps its dual γ' has no inflection points. The dual γ' has $\#'_{cusps} = 3(d-2)$ cusps and genus 0. Therefore its number $\#'_{nodes}$ of nodes equals $\binom{2d-3}{2} - 3d + 6 = \frac{(2d-3)(2d-4)}{2} - 3d + 6 = 2d^2 - 10d + 12 = 2(d-2)(d-3)$. \square

Lemma 17. (1) For a generic plane curve γ of degree d , its evolute $E_\gamma \subset \mathbb{C}P^2$ is a plane curve of degree $d_E = 3d(d-1)$ and class $d'_E = d^2$. E_γ has no inflection points, $\#^E_{cusps} = d(6d-9)$ cusps and $\#^E_{nodes} = \frac{d(3d-5)(3d^2-d-6)}{2}$ nodes. The number $\#^N_{nodes}$ of nodes of $\tilde{N}_\Gamma^{\mathbb{C}}$ equals $\binom{d^2-1}{2} - \binom{d-1}{2} = \frac{d(d-1)(d^2+d-3)}{2}$. There are no cusps on $\tilde{N}_\Gamma^{\mathbb{C}}$ (since \tilde{E}_Γ has no inflection points).

(2) For a generic rational curve γ of degree d , its evolute $E_\gamma \subset \mathbb{C}P^2$ is a rational curve of degree $d_E = 6(d-1)$ and class $d'_E = 3d-2$. E_γ has no inflection points,

$\#_{cusps}^E = 3(3d-4)$ cusps and $\#_{nodes}^E = 2(3d-4)(3d-5)$ nodes. The curve of normals $N_\gamma \subset (\mathbb{C}P^2)^*$ (i.e. the dual curve to the evolute E_γ) has no cusps, $\binom{3d-3}{2}$ nodes and $3(3d-4)$ inflection points.

Proof. A generic rational curve γ satisfies the assumptions of Theorem 54 of [4]. Thus, by Theorem 54, the degree d_E of the evolute E_γ is given by $d_E = 3d + \#_i = 3d + 3(d-2) = 6(d-1)$. The class d'_E of E_γ equals $d + d' = d + 2d - 2 = 3d - 2$. Thus the curve of normals N_γ has degree $3d - 2$ and genus 0. Since, by Theorem 54, the evolute E_γ has no inflection points the curve N_γ has no cusps. Thus N_γ has $\#_{nodes}^N = \binom{3d-3}{2}$ nodes. Finally, its number $\#_i^N$ of inflection points equals $3(3d-2)(3d-4) - 6\#_{nodes}^N = 9d - 12$. \square

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